

How to ride the wave of innovative mechatronics?

19 June 2018

Bart van Dartel | Utrecht

How to ride the wave of innovative mechatronics?

19 June 2018

Bart van Dartel | Utrecht

Introduction

VANDERLANDE

Research & Development

STORK[®]
Fokker

TU/e Mechanical Engineering



*Reliable partner for value-added
logistic process automation*



Airports



Warehousing



Parcel



About Vanderlande: Company profile



Industry Segments: Airports



Industry Segments: Warehousing



Industry segments: Parcel



**We improve the competitiveness of our customers
through value-added material handling solutions**

Growth

Innovation

Internationalisation

Teamwork

Innovation: Different approaches

Processes & Methods



One way of working

(ISO, Process Map)



Modernization

(Agile, Model Based Design)

Products



Technology push



Market pull

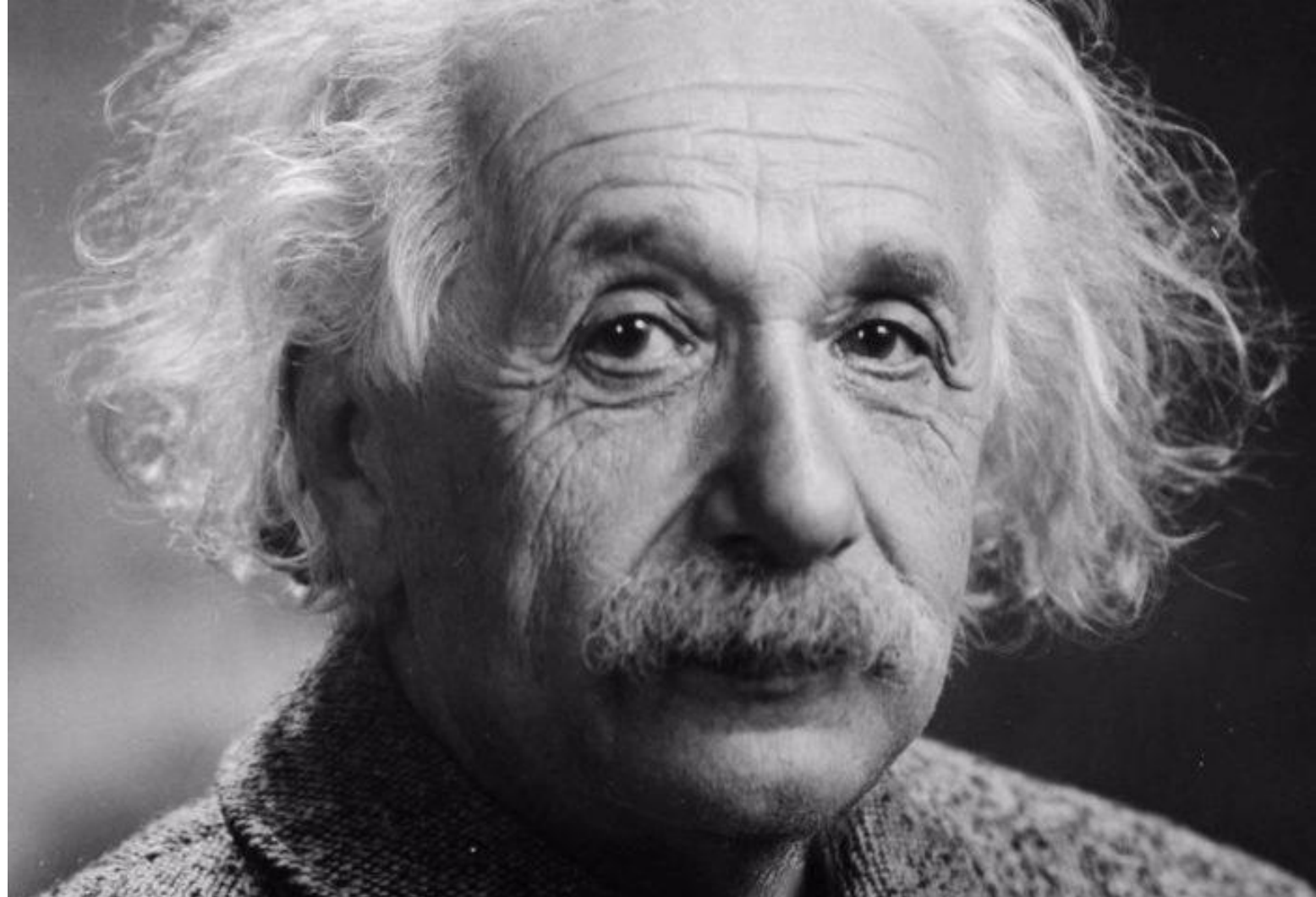


**Co-creation
with key customers**

Start with Why



“ Everything should be made as simple as possible, **but not simpler.** ”



Future solutions: Need for automated item handling



- > More and more tasks can be automated with robot applications
- > One by one, robots will take over responsibility of current operators tasks
- > Operators will oversee a number of robots and eventually oversee whole operation from the control room
- > Resulting in a fully automated flexible warehouse running 24/7 with a higher productivity, optimized output and minimum of errors in product handling

Our Challenges: Diversity in a critical process

Carriers

- ULD Aircrafts, Pallets, Trailers/dollies, Swap bodies, roll cages
- All different sizes and shapes
- High filling rate required

Items

- Very large number or indefinite number of items
- All types shapes, weights, quality, surfaces
- Content of the items sometimes unknown

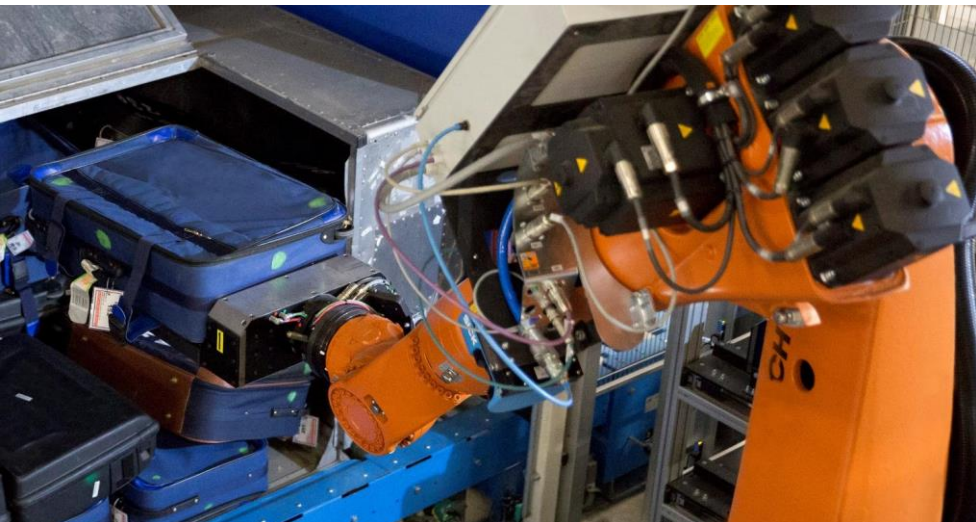
Process

- Time critical and capacity is key
- Operator handles variety of exceptions
- Value Added Services if applicable

About R&D: (Mobile) Robotics & Item Handling

Robotic Item Handling:

- > Machine Vision
- > Deep Learning
- > Gripping



Mobile Robotics:

- > Semantic World Modelling
- > Operate autonomously in changing environments



SYSTEM
DEVELOPMENT



MECHATRONICS



HUMAN
INTERACTION



ROBOTIC / AGV
SOLUTIONS



COGNITIVE
ABILITY



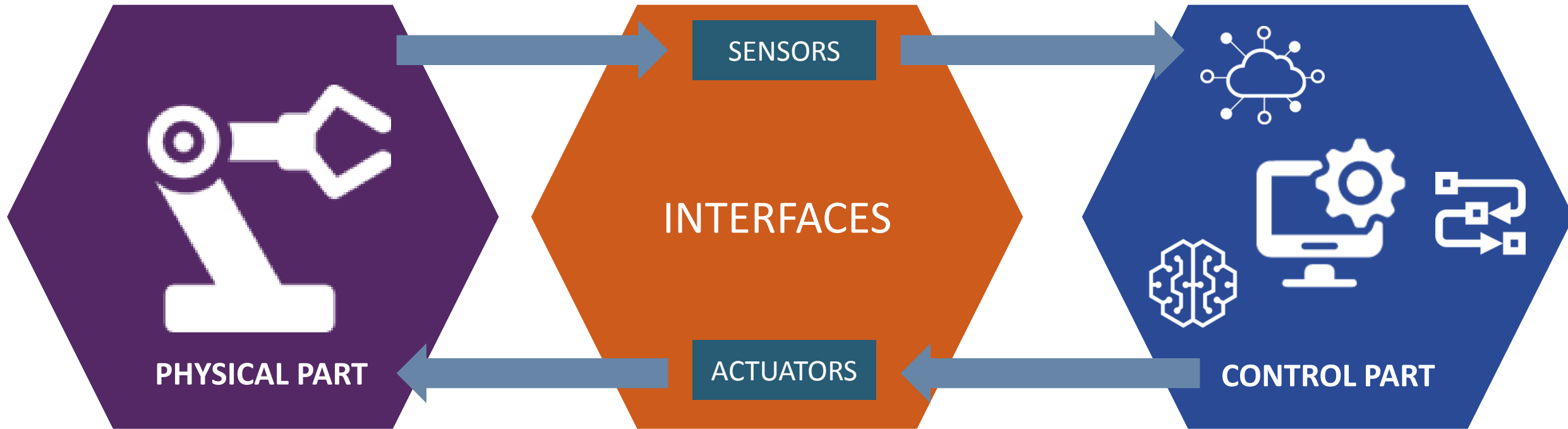
PERCEPTION



NAVIGATION



Transition: Adding brains to mechatronics



~~Mechatronics~~ → CyberPhysical

Κυβερνητική

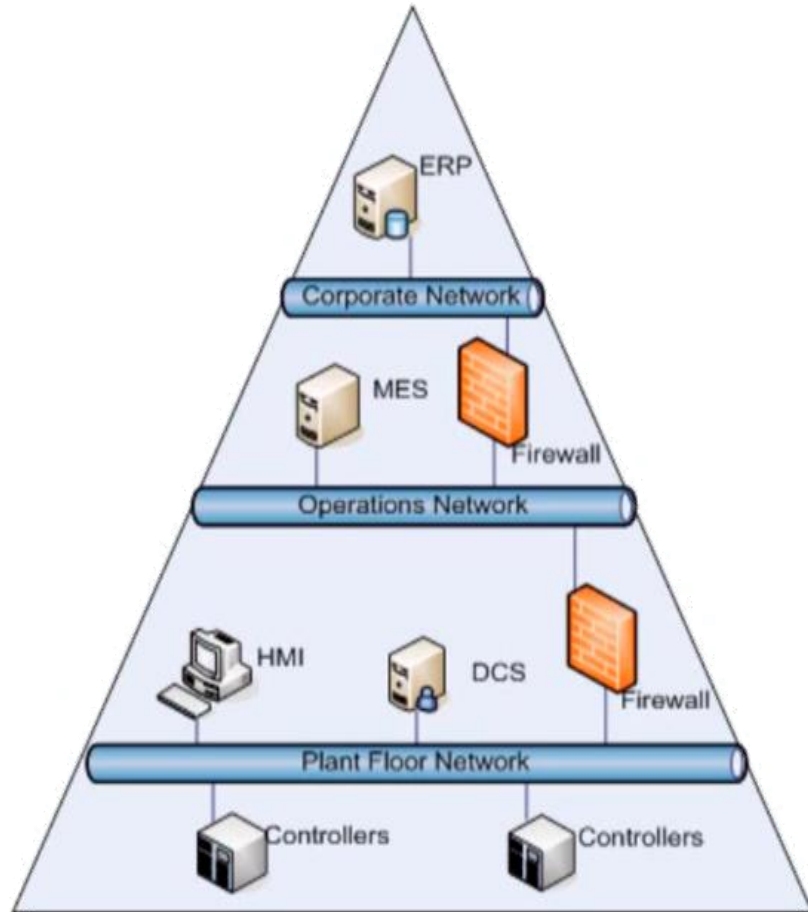
Governance





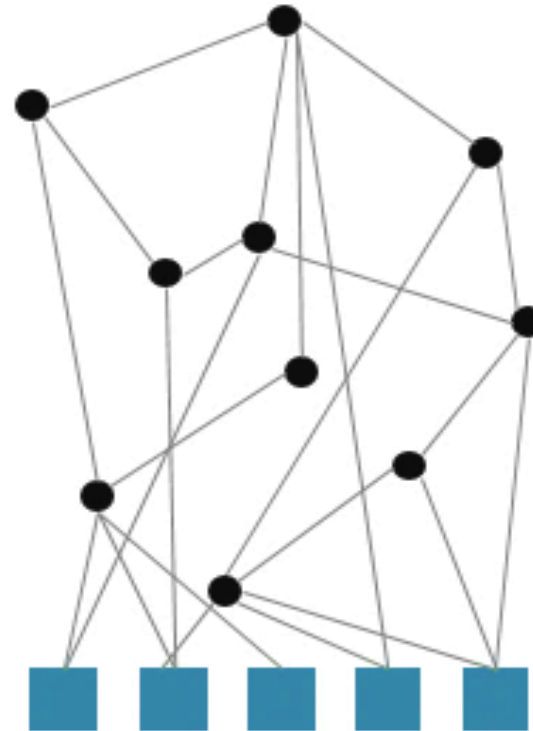
Today

5-layer architecture

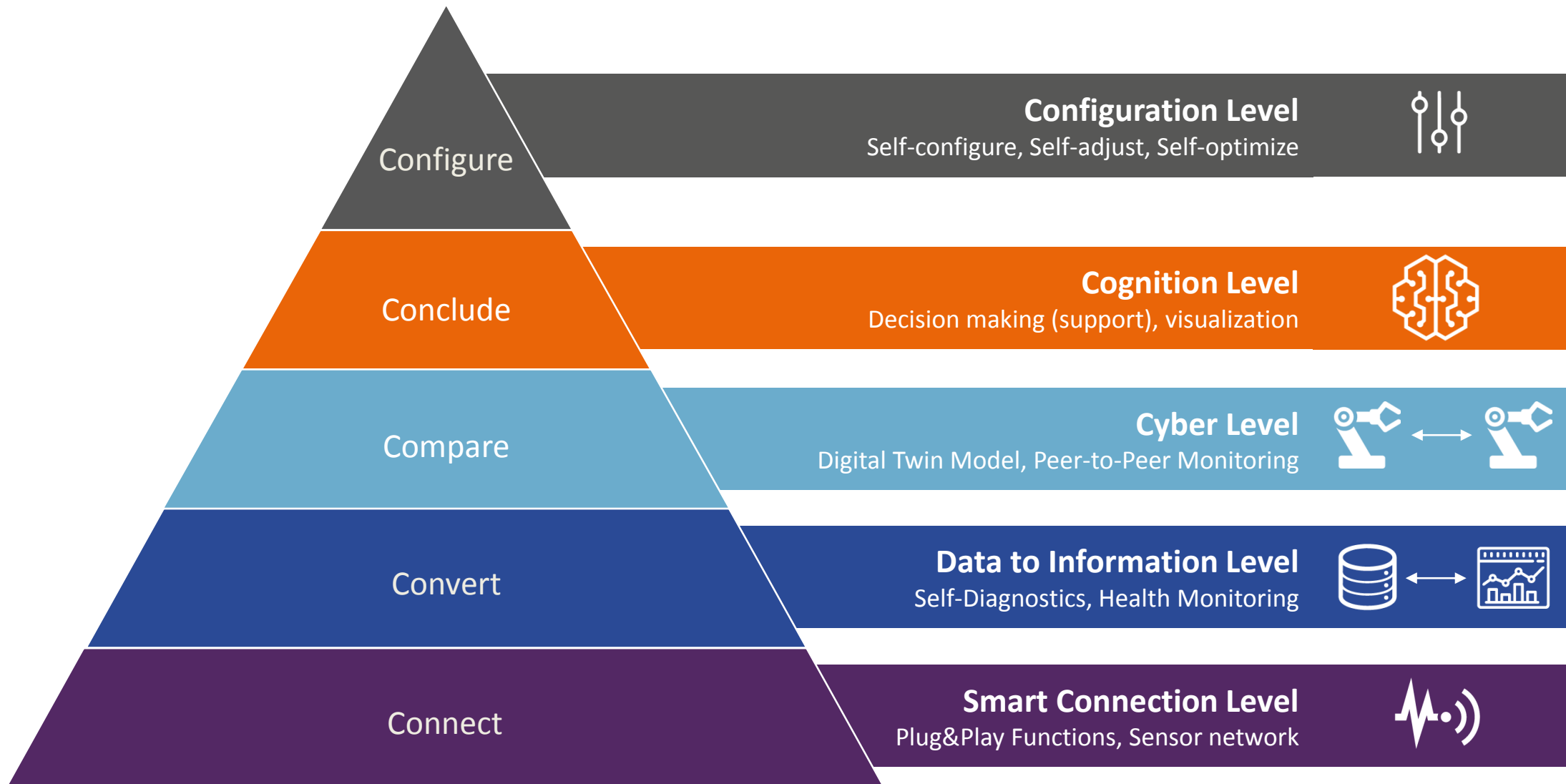


Future

Cyber-physical system (CPS) based automation



Data architecture for Cyberphysical systems



A cyberphysical example



Bring new learnings
to all vehicles



Learning: It is better to
follow an alternative path



An alternative path
is simulated by virtual twin



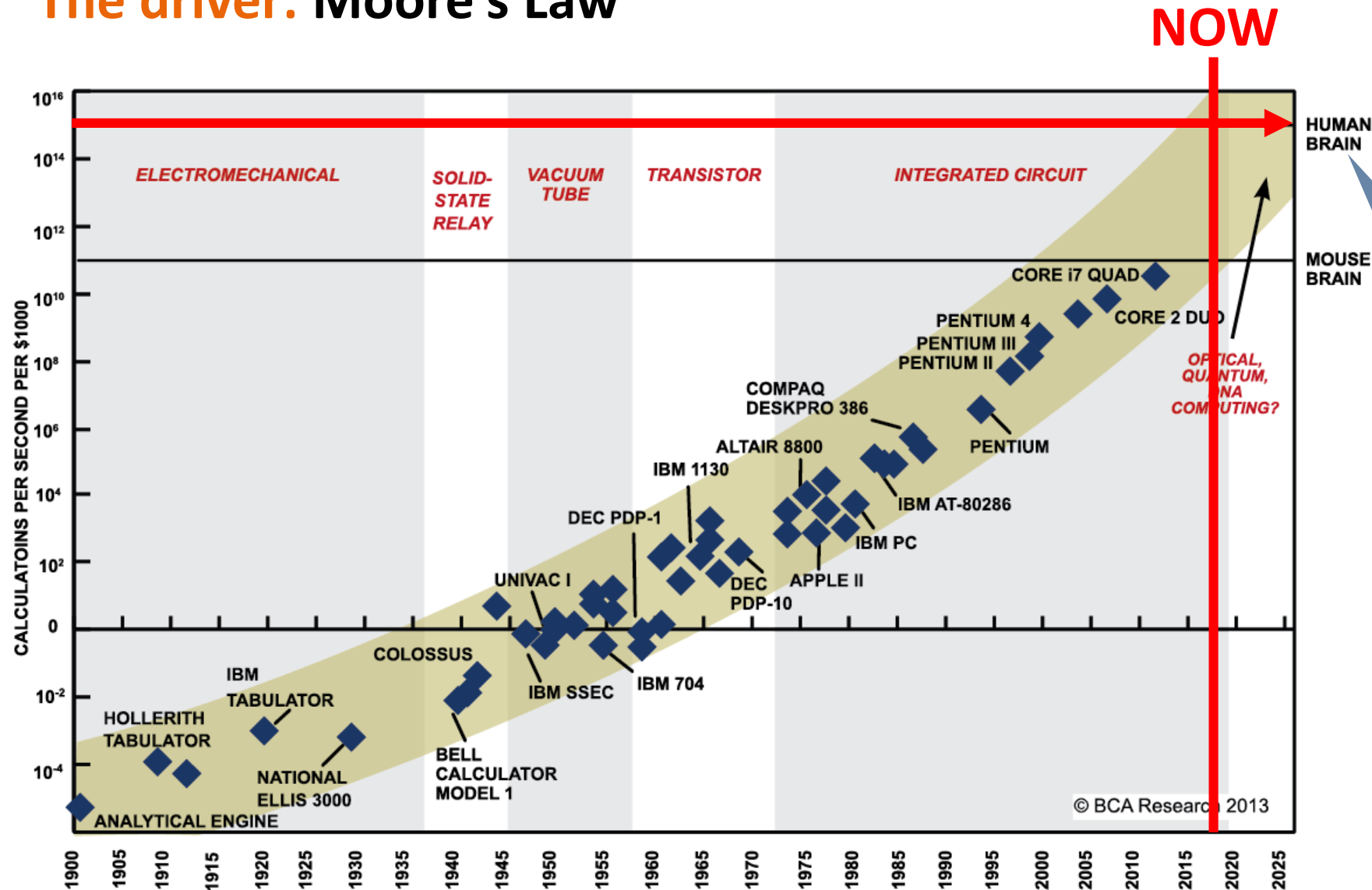
It reduced my performance
with 20%



I see and report an obstacle on my path



The driver: Moore's Law

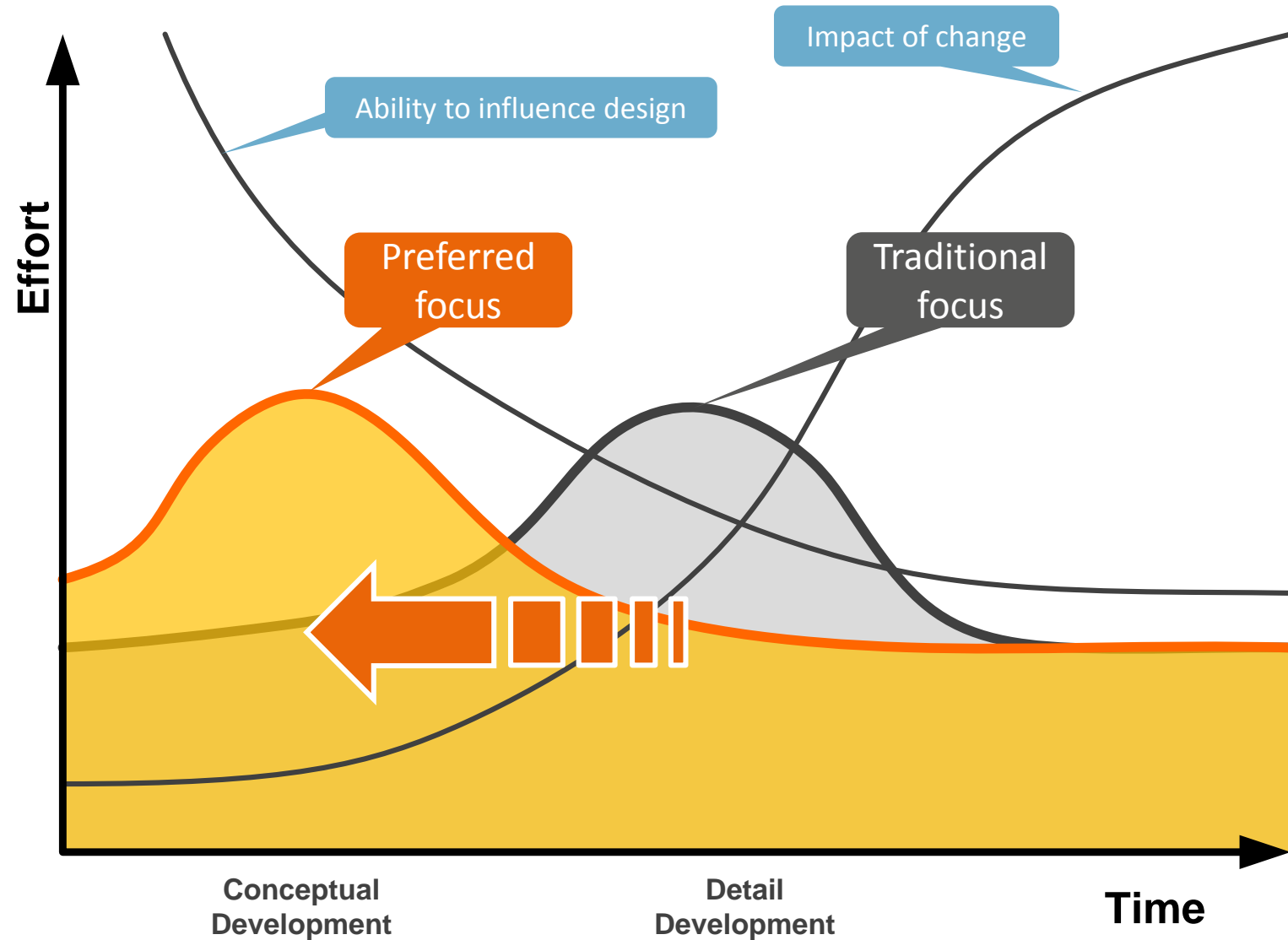


< 10 years!

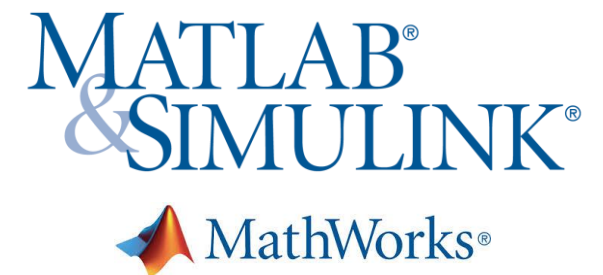
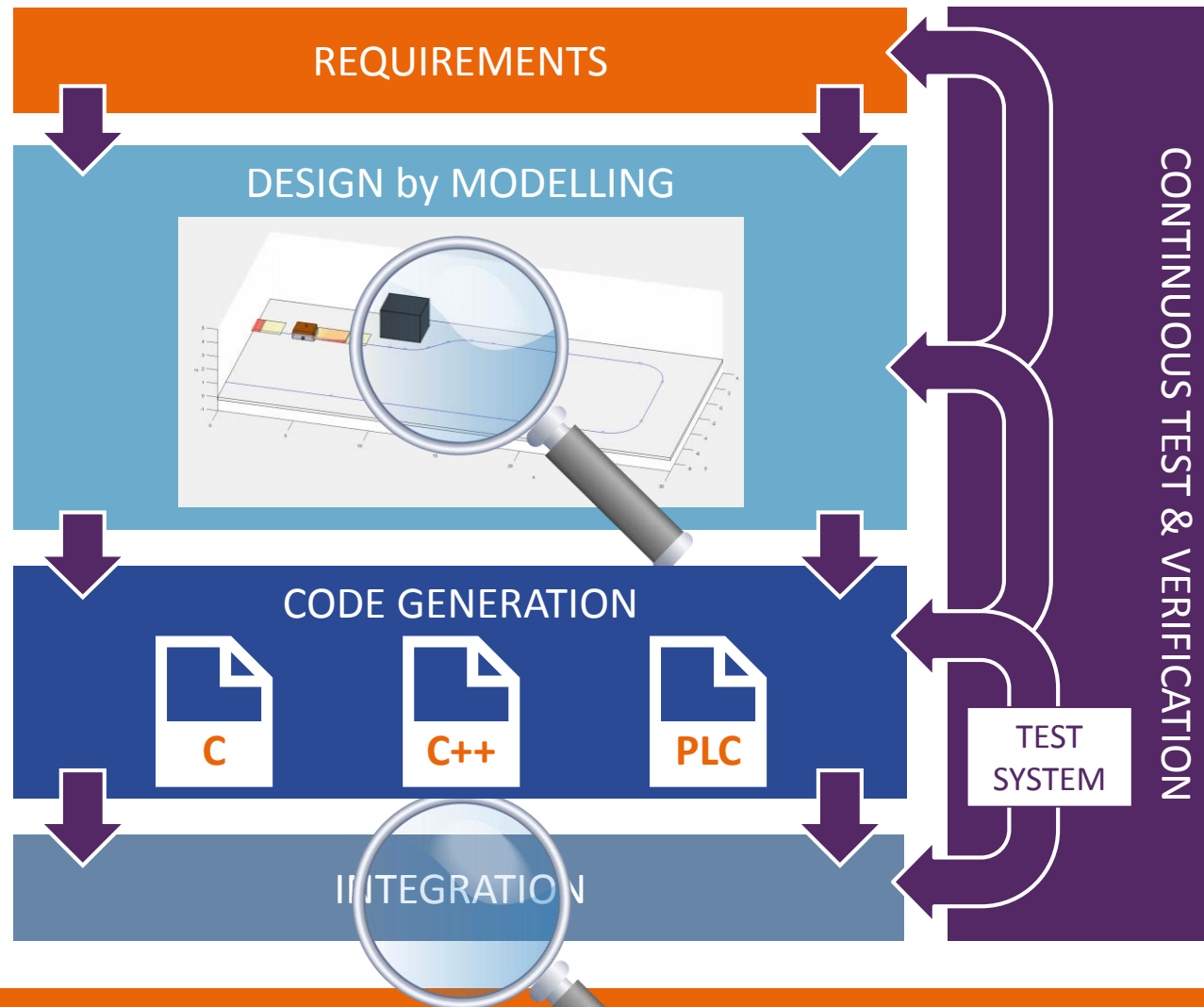
Source: Kurzweil R. *The singularity is near: When humans transcend biology*

Setting the focus

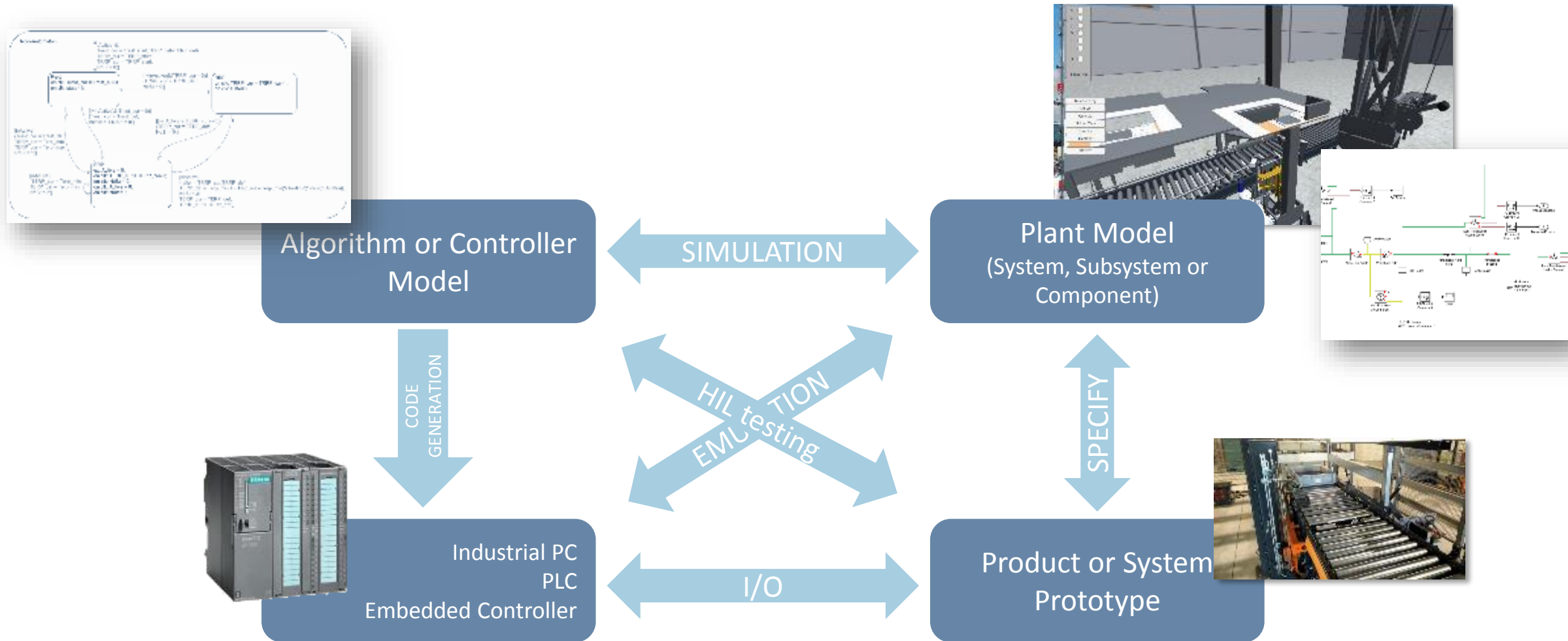
- Ability to influence design and roadmap
- Act swift and agile on customer demands
- Prepare design work for partners
- Automation of design work

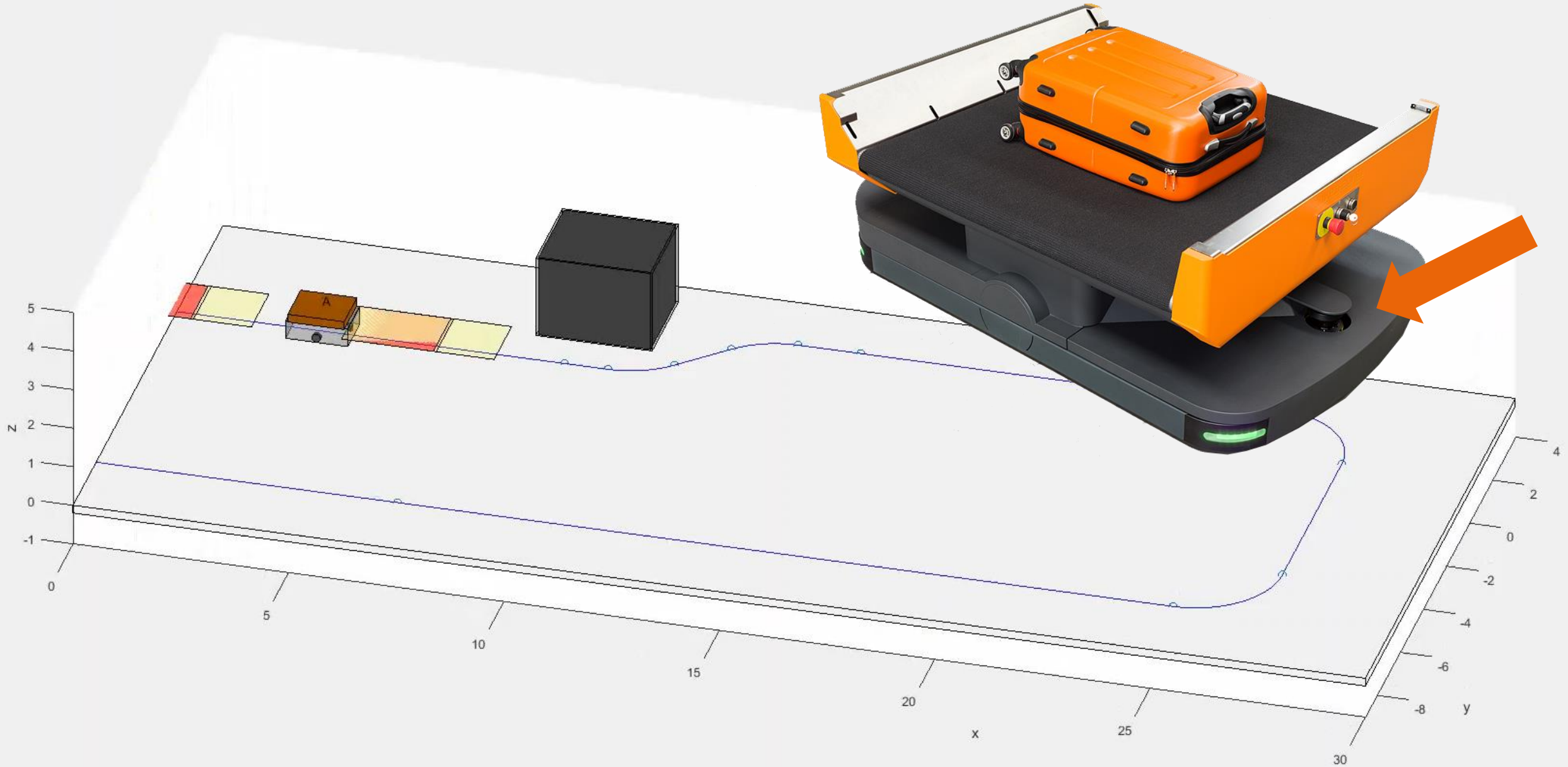


Model Based Design: Focus on design & integration

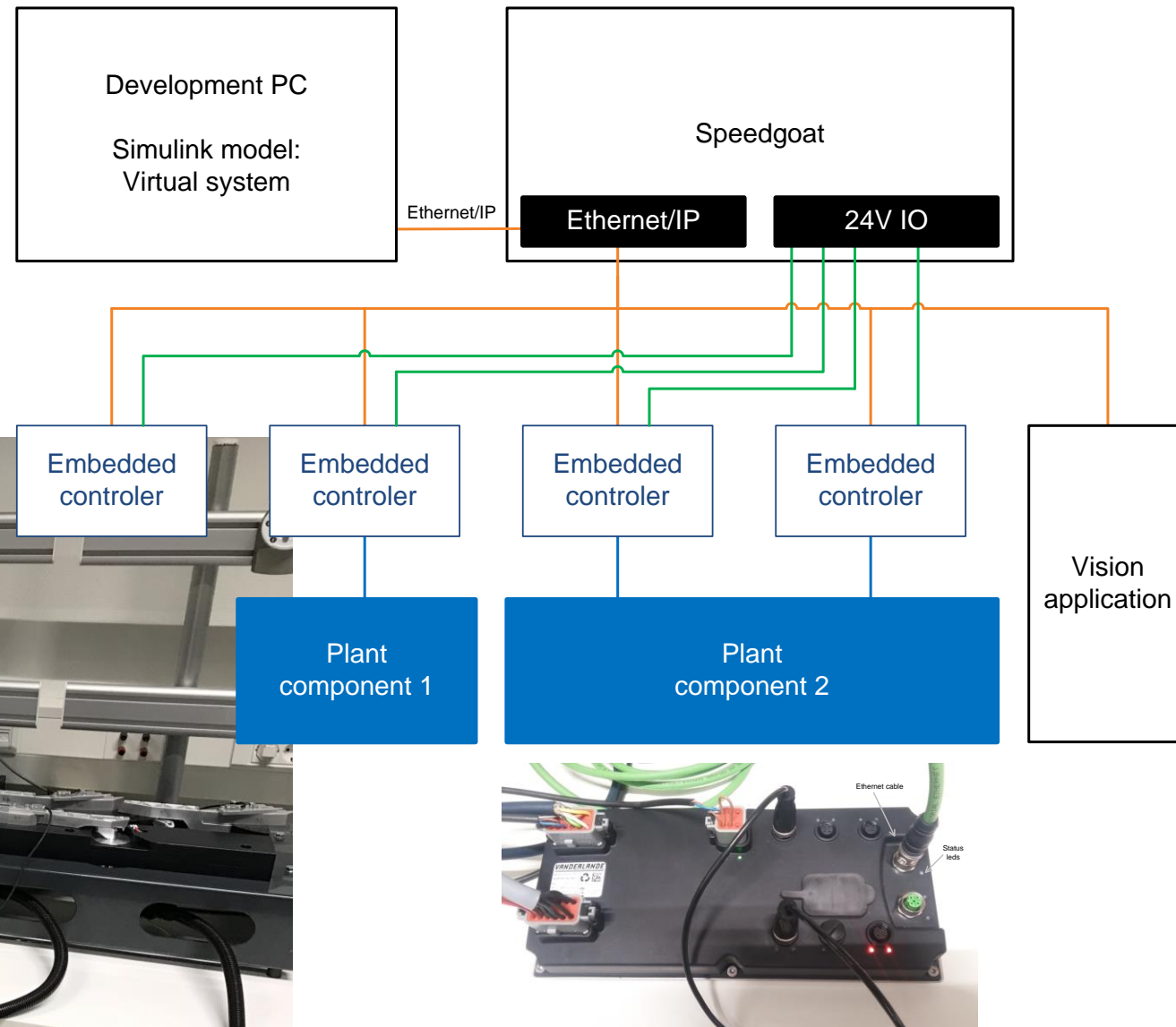


Model Based Design: Creation of a virtual world





Continuous Test & Verification



Development Teams: A knowledge Ecosystem approach

Autonomous

Cross-functional

Many interactions

Models as technical truth



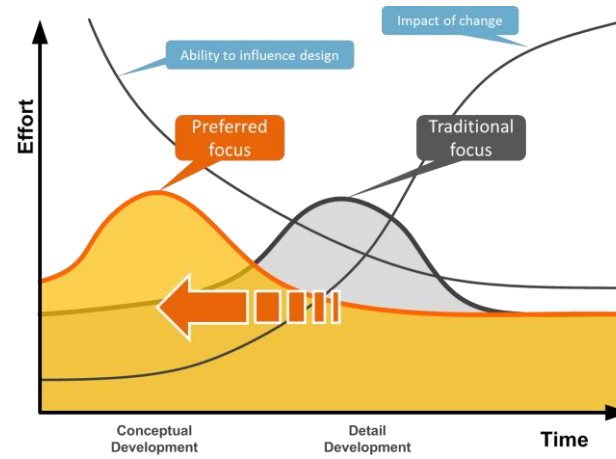
Partnership approach



Complex Cyberphysical Systems



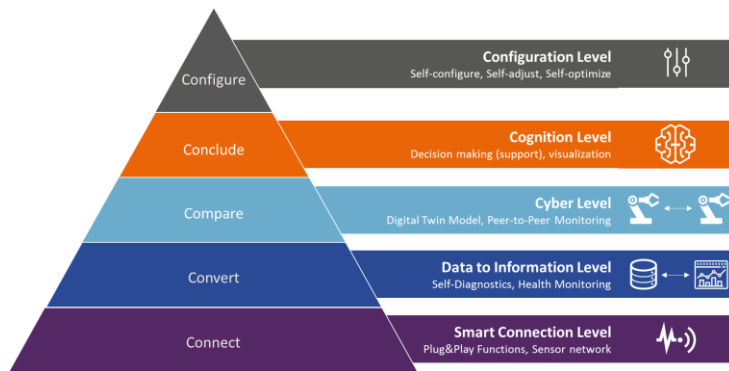
Shift of Focus



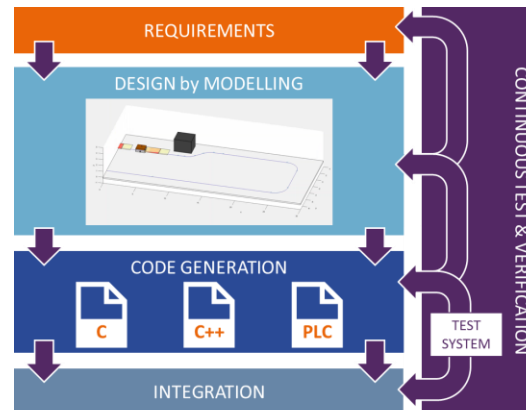
Autonomous Teams



Architecture



Design Automation



Partnership approach



A full-page background image of a surfer riding a large, curling wave. The surfer is positioned in the lower right quadrant of the frame, riding the face of the wave. The wave is a deep teal color with white foam at the crest. The sky is a clear, light blue.

How to ride the wave of innovative mechatronics? *Embrace complexity and work together!*

19 June 2018